

COORDINATE POLARI PIANE

vettore posizione: $\mathbf{r} = r \cos \theta \hat{\mathbf{x}} + r \sin \theta \hat{\mathbf{y}}$

$$\begin{aligned} \text{trasformazione: } r &= \sqrt{x^2 + y^2} & x &= r \cos \theta \\ \theta &= \tan^{-1}(y, x) & y &= r \sin \theta \end{aligned}$$

elemento di area: $dV = r dr d\theta$

campo scalare: $f(r, \theta)$

$$\text{gradiente: } \nabla f = \frac{\partial f}{\partial r} \hat{\mathbf{r}}(\theta) + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\boldsymbol{\theta}}(\theta)$$

$$\text{laplaciano: } \nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

$$\text{advezione: } \mathbf{a} \cdot \nabla f = a_r \frac{\partial f}{\partial r} + \frac{a_\theta}{r} \frac{\partial f}{\partial \theta}$$

$$\text{fattori di scala: } h_r = \left| \frac{\partial \mathbf{r}}{\partial r} \right| = 1, \quad h_\theta = \left| \frac{\partial \mathbf{r}}{\partial \theta} \right| = r$$

$$\begin{aligned} \text{base locale: } \hat{\mathbf{r}}(\theta) &= \cos \theta \hat{\mathbf{x}} + \sin \theta \hat{\mathbf{y}} & \hat{\mathbf{x}} &= \cos \theta \hat{\mathbf{r}}(\theta) - \sin \theta \hat{\boldsymbol{\theta}}(\theta) \\ \hat{\boldsymbol{\theta}}(\theta) &= -\sin \theta \hat{\mathbf{x}} + \cos \theta \hat{\mathbf{y}} & \hat{\mathbf{y}} &= \sin \theta \hat{\mathbf{r}}(\theta) + \cos \theta \hat{\boldsymbol{\theta}}(\theta) \end{aligned}$$

campo vettoriale: $\mathbf{F}(r, \theta) = F_r(r, \theta) \hat{\mathbf{r}}(\theta) + F_\theta(r, \theta) \hat{\boldsymbol{\theta}}(\theta)$

$$\text{divergenza: } \nabla \cdot \mathbf{F} = \frac{1}{r} \frac{\partial}{\partial r} (r F_r) + \frac{1}{r} \frac{\partial F_\theta}{\partial \theta}$$

$$\text{rotore: } \nabla \times \mathbf{F} = \left[\frac{1}{r} \frac{\partial}{\partial r} (r F_\theta) - \frac{1}{r} \frac{\partial F_r}{\partial \theta} \right] \hat{\mathbf{z}}$$

$$\begin{aligned} \text{lapl. vett.: } \nabla^2 \mathbf{F} &= \left[\nabla^2 F_r - \frac{F_r}{r^2} - \frac{2}{r^2} \frac{\partial F_\theta}{\partial \theta} \right] \hat{\mathbf{r}}(\theta) \\ &+ \left[\nabla^2 F_\theta - \frac{F_\theta}{r^2} + \frac{2}{r^2} \frac{\partial F_r}{\partial \theta} \right] \hat{\boldsymbol{\theta}}(\theta) \end{aligned}$$

$$\begin{aligned} \text{advez.: } (\mathbf{a} \cdot \nabla) \mathbf{F} &= \left[a_r \frac{\partial F_r}{\partial r} + \frac{a_\theta}{r} \left(\frac{\partial F_r}{\partial \theta} - F_\theta \right) \right] \hat{\mathbf{r}}(\theta) \\ &+ \left[a_r \frac{\partial F_\theta}{\partial r} + \frac{a_\theta}{r} \left(\frac{\partial F_\theta}{\partial \theta} + F_r \right) \right] \hat{\boldsymbol{\theta}}(\theta) \end{aligned}$$

COORDINATE CILINDRICHE

vettore posizione: $\mathbf{r} = R \cos \theta \hat{\mathbf{x}} + R \sin \theta \hat{\mathbf{y}} + z \hat{\mathbf{z}}$

$$\begin{aligned} \text{trasformazione: } R &= \sqrt{x^2 + y^2} & x &= R \cos \theta \\ \theta &= \tan^{-1}(y, x) & y &= R \sin \theta \\ z &= z & z &= z \end{aligned}$$

elemento di volume: $dV = R dR d\theta dz$

campo scalare: $f(R, \theta, z)$

$$\text{gradiente: } \nabla f = \frac{\partial f}{\partial R} \hat{\mathbf{R}}(\theta) + \frac{1}{R} \frac{\partial f}{\partial \theta} \hat{\boldsymbol{\theta}}(\theta) + \frac{\partial f}{\partial z} \hat{\mathbf{z}}$$

$$\text{laplaciano: } \nabla^2 f = \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial f}{\partial R} \right) + \frac{1}{R^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2}$$

$$\text{advezione: } \mathbf{a} \cdot \nabla f = a_R \frac{\partial f}{\partial R} + \frac{a_\theta}{R} \frac{\partial f}{\partial \theta} + a_z \frac{\partial f}{\partial z}$$

$$\text{fattori di scala: } h_R = \left| \frac{\partial \mathbf{r}}{\partial R} \right| = 1, \quad h_\theta = \left| \frac{\partial \mathbf{r}}{\partial \theta} \right| = R, \quad h_z = \left| \frac{\partial \mathbf{r}}{\partial z} \right| = 1$$

$$\begin{aligned} \text{base locale: } \hat{\mathbf{R}}(\theta) &= \cos \theta \hat{\mathbf{x}} + \sin \theta \hat{\mathbf{y}} & \hat{\mathbf{x}} &= \cos \theta \hat{\mathbf{R}}(\theta) - \sin \theta \hat{\boldsymbol{\theta}}(\theta) \\ \hat{\boldsymbol{\theta}}(\theta) &= -\sin \theta \hat{\mathbf{x}} + \cos \theta \hat{\mathbf{y}} & \hat{\mathbf{y}} &= \sin \theta \hat{\mathbf{R}}(\theta) + \cos \theta \hat{\boldsymbol{\theta}}(\theta) \end{aligned}$$

campo vett.: $\mathbf{F}(R, \theta, z) = F_R(R, \theta, z) \hat{\mathbf{R}}(\theta) + F_\theta(R, \theta, z) \hat{\boldsymbol{\theta}}(\theta) + F_z(R, \theta, z) \hat{\mathbf{z}}$

$$\text{divergenza: } \nabla \cdot \mathbf{F} = \frac{1}{R} \frac{\partial}{\partial R} (R F_R) + \frac{1}{R} \frac{\partial F_\theta}{\partial \theta} + \frac{\partial F_z}{\partial z}$$

$$\begin{aligned} \text{rotore: } \nabla \times \mathbf{F} &= \left[\frac{1}{R} \frac{\partial F_z}{\partial \theta} - \frac{\partial F_\theta}{\partial z} \right] \hat{\mathbf{R}}(\theta) + \left[\frac{\partial F_R}{\partial z} - \frac{\partial F_z}{\partial R} \right] \hat{\boldsymbol{\theta}}(\theta) \\ &+ \left[\frac{1}{R} \frac{\partial}{\partial R} (R F_\theta) - \frac{1}{R} \frac{\partial F_R}{\partial \theta} \right] \hat{\mathbf{z}} \end{aligned}$$

$$\begin{aligned} \text{lapl. vett.: } \nabla^2 \mathbf{F} &= \left[\nabla^2 F_R - \frac{F_R}{R^2} - \frac{2}{R^2} \frac{\partial F_\theta}{\partial \theta} \right] \hat{\mathbf{R}}(\theta) \\ &+ \left[\nabla^2 F_\theta - \frac{F_\theta}{R^2} + \frac{2}{R^2} \frac{\partial F_R}{\partial \theta} \right] \hat{\boldsymbol{\theta}}(\theta) \\ &+ \left[\nabla^2 F_z \right] \hat{\mathbf{z}} \end{aligned}$$

$$\begin{aligned} \text{advez.: } (\mathbf{a} \cdot \nabla) \mathbf{F} &= \left[\mathbf{a} \cdot \nabla F_R - \frac{a_\theta F_\theta}{R} \right] \hat{\mathbf{R}}(\theta) + \left[\mathbf{a} \cdot \nabla F_\theta + \frac{a_\theta F_R}{R} \right] \hat{\boldsymbol{\theta}}(\theta) \\ &+ \left[\mathbf{a} \cdot \nabla F_z \right] \hat{\mathbf{z}} \\ &= \left[a_R \frac{\partial F_R}{\partial R} + \frac{a_\theta}{R} \left(\frac{\partial F_R}{\partial \theta} - F_\theta \right) + a_z \frac{\partial F_R}{\partial z} \right] \hat{\mathbf{R}}(\theta) \\ &+ \left[a_R \frac{\partial F_\theta}{\partial R} + \frac{a_\theta}{R} \left(\frac{\partial F_\theta}{\partial \theta} + F_R \right) + a_z \frac{\partial F_\theta}{\partial z} \right] \hat{\boldsymbol{\theta}}(\theta) \\ &+ \left[a_R \frac{\partial F_z}{\partial R} + \frac{a_\theta}{R} \frac{\partial F_z}{\partial \theta} + a_z \frac{\partial F_z}{\partial z} \right] \hat{\mathbf{z}} \end{aligned}$$